Abhishek lyer Software Engineer, Al and Robotics

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Pittsburgh, USA 📕 Australian

EDUCATION

Carnegie Mellon University, Masters in Robotics Systems Development

08.2024 – 05.2026 | Pittsburgh, USA

08.2018 - 05.2022 | Pilani, India

Birla Institute of Technology and Science (BITS) Pilani,

B.E Electrical and Electronics, Major GPA: 8.51/10

PUBLICATIONS

[1] CoColor: Interactive Exploration of Color Designs

[2] CNN and LSTM based Ensemble Learning for Human Emotion Recognition using EEG Recordings 🗵

[3] Eformer: Edge Enhancement based Transformer for Medical Image Denoising

[4] Modelling, Simulation, and Implementation of PID controller on Quadrotors

PROFESSIONAL EXPERIENCE

Indian Institute of Science (IISc), Research Assistant

11.2023 – present | Bangalore, India

Advisor: Prof. Rajiv Soundararajan 🗹

- Solving high-level semantic issues in AI-generated images such as conjoined limbs and disfigured faces by leveraging **vision-language models** for assessing application-specific perceptual quality.
- Improving 3D scene understanding by researching novel view synthesis using Neural Radiance Fields (NeRFs).

Design.Al, Software Development Engineer ☑

08.2022 – 07.2023 | Espoo, Finland

- Researched and implemented deep learning models such as Large Language Models (LLMs), Gaze Estimation models, and Convolutional Neural Network (CNN) classifiers.
- Implemented classic techniques such as algorithms on custom Tree and Graph structures for guideline evaluation and optimization models for creative exploration.
- Quality Assurance and regression testing against benchmark suite.

Aalto University, Research Assistant

08.2021 – 08.2022 | Espoo, Finland

Advisor: Prof. Antti Oulasvirta 🛭

- Researched and implemented saliency estimation deep learning models for focal object detection in a given UI.
- Improved Modified Median Color Quantization (MMCQ) algorithm for extracting coherent color palette.
- Used Monte Carlo Tree Search (MCTS) and Gaussian Mixed Models (GMMs) to extend the initial color palette.

Johannes Kepler University, Bachelor Thesis

07.2021 – 12.2021 | Linz, Austria

Advisors: Prof. Oliver Bimber 🗷 , Prof. Shishir Maheshwari 🗹

- Developed an object detection model that can perform real-time classification of humans under dense canopies.
- Used Reed-Xiaoli Detector to identify colour changes and generate anchor boxes in only those regions to keep the model lightweight. Used **Airborne Optical Sectioning (AOS)** technique to preprocess input images.

Computer Vision Research Society (CVRS), $Team\ Lead\ extcolor{}$

02.2021 – 12.2021 | Pilani, India

- Our model is composed of an encoder-decoder network using transformer blocks, Sobel-Feldman operators for edge enhancement, and residual learning.
- The architecture achieved **state-of-the-art results** on the AAPM-Mayo Clinic Low-Dose CT Ground Challenge dataset.

AcYut Robotics Team, Core Member

08.2018 – 05.2019 | Pilani, India

- AcYut is a collegiate technical team which has represented India in autonomous humanoid robotics competitions.
- My role focused on designing motor controllers and encoders for our in house programmable motors.
- Research and simulation of navigation strategies for the robot.

PROJECTS

EEG signal analysis using Machine learning, Worked under Dr. Shishir Maheshwari and Dr. Rishi Raj Sharma

• Achieved state-of-the-art performance for emotion classification on the SEED Dataset with a novel ensemble model.

Sensor fusion techniques for manipulation of Robotic arm, Worked under Dr. Meetha Shenoy

• Implemented a genetic evolution movement algorithm to optimize throughput for multiple robotic arms in ROS.

Marine Search and Rescue

• Implemented models like Faster-RCNN and Deep SORT to perform object detection and Multi-Object Tracking, respectively. Created custom dataset, dataloaders, and processing pipeline to train on local GPU.

TECHNICAL SKILLS

Languages

Abhishek Iver

Python, C++, Matlab, Arduino

Tools and Frameworks

PyTorch, Tensorflow, ROS2, Gazebo, OpenCV, Numpy, Pandas, Matlab, Eagle

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